CS 301

Lecture 13 - Closure properties of context-free languages

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March 5, 2018



CFLs and PDAs

Theorem

Every context-free language can be recognized by some PDA.

Proof idea.

- **1** Use the PDA's stack to perform a left-most derivation of a word in the language
- 2 Match the PDA's input symbols against the stack, popping each one
- 3 Accept if stack is empty when there's no more input



Consider the language $A = \{w \mid w \in \{a, b\}^* \text{ and } w \text{ is not a palindrome}\}$ What CFG generates that language?



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$$\begin{split} S &\to aSa \mid bSb \mid aTb \mid bTa \\ T &\to aT \mid bT \mid \varepsilon \end{split}$$



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A left-most derivation of the string $abaaa \ \mbox{is}$

 $S \Rightarrow aSa \Rightarrow abTaa \Rightarrow abaTaa \Rightarrow abaaa.$

We want to start by pushing S on the stack, then performing the derivation step by step so that abaaa ends on the stack, and then match the input



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There are two complications

- \blacksquare The first step in the derivation $S \Rightarrow aSa$ requires popping one symbol and pushing three
- 2 We can only replace symbols at the top of the stack



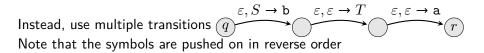
Pushing multiple symbols

We would like to write a transition like qbut $\delta: Q \times \Sigma_{\varepsilon} \times \Gamma_{\varepsilon} \to P(Q \times \Gamma_{\varepsilon})$ doesn't allow that



Pushing multiple symbols

We would like to write a transition like $q \xrightarrow{\varepsilon, S \to aTb} r$ but $\delta: Q \times \Sigma_{\varepsilon} \times \Gamma_{\varepsilon} \to P(Q \times \Gamma_{\varepsilon})$ doesn't allow that





We can only replace symbols at the top of the stack

Rather than first deriving the whole string on the stack and then matching the input,

• If the top of the stack is a terminal, match it to the next input symbol

 $\xrightarrow{t, t \to \varepsilon} for each t \in \Sigma$

• If the top of the stack is a variable, replace it with the RHS of a corresponding rule



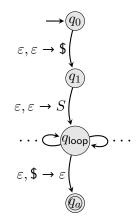
We can only replace symbols at the top of the stack

Rather than first deriving the whole string on the stack and then matching the input,

- If the top of the stack is a terminal, match it to the next input symbol $t, t \to \varepsilon$ for each $t \in \Sigma$
- If the top of the stack is a variable, replace it with the RHS of a corresponding rule

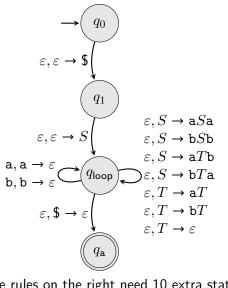
In fact, we only need four main states plus any additional states necessary to push multiple symbols

The q_{loop} state is where all the real work happens



Example

- $$\begin{split} S &\to \mathbf{a} S \mathbf{a} \mid \mathbf{b} S \mathbf{b} \mid \mathbf{a} T \mathbf{b} \mid \mathbf{b} T \mathbf{a} \\ T &\to \mathbf{a} T \mid \mathbf{b} T \mid \varepsilon \end{split}$$
- For each $t \in \Sigma$, add the transition $t, t \rightarrow \varepsilon$ from q_{loop} to q_{loop}
- Por each rule A → u₁u₂····u_n for u_i ∈ V ∪ Σ, add n − 1 new states (if n > 1) and transitions to pop A and push u₁, u₂,..., u_n on in reverse order



[The rules on the right need 10 extra states uc to make this a proper PDA]

Consider running the PDA on the input abaaa. The stack is shown on the right after each step

\$

1 push \$;

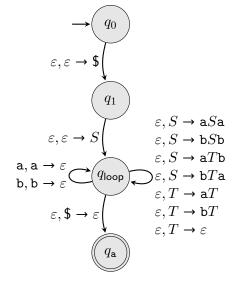
 q_0 ε, ε q_1 $\begin{array}{l} \varepsilon,S \rightarrow \mathbf{a}S\mathbf{a} \\ \varepsilon,S \rightarrow \mathbf{b}S\mathbf{b} \end{array}$ $\varepsilon, \varepsilon \rightarrow$ $\varepsilon, S \rightarrow aTb$ $a, a \rightarrow \varepsilon$) $\varepsilon, S \rightarrow bTa$ q_{loop} $\varepsilon, T \rightarrow \mathbf{a}T$ $\begin{array}{l} \varepsilon,T \rightarrow \mathbf{b}T\\ \varepsilon,T \rightarrow \varepsilon \end{array}$ $\varepsilon, \$ \rightarrow$ $q_{\mathtt{a}}$



Consider running the PDA on the input abaaa. The stack is shown on the right after each step

- **1** push \$;
- 2 push S;

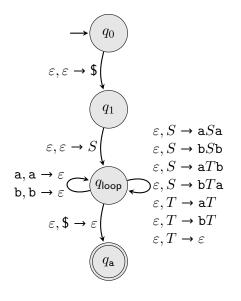
\$ *S*\$



Consider running the PDA on the input abaaa. The stack is shown on the right after each step

- push \$; \$
- 2 push S; S
- **3** pop S, push aSa;

aSa\$



Consider running the PDA on the input abaaa. The stack is shown on the right after each step

- 1 push \$;
- 2 push S; S

\$

aSa

Sa

- **3** pop S, push aSa;
- 4 read and pop a;

 q_0 $\varepsilon, \varepsilon \rightarrow$ q_1 $\varepsilon,S \to \mathbf{a}S\mathbf{a}$ $\varepsilon, S \rightarrow bSb$ $\varepsilon, \varepsilon \rightarrow$ $\varepsilon, S \rightarrow aTb$ $\mathtt{a},\mathtt{a} \to \varepsilon$ q_{loop} $\varepsilon, S \rightarrow bTa$ $\varepsilon, T \rightarrow \mathbf{a}T$ $\begin{array}{l} \varepsilon,T \rightarrow \mathbf{b}T\\ \varepsilon,T \rightarrow \varepsilon \end{array}$ $\varepsilon, \$ \rightarrow$ q_{a}



Consider running the PDA on the input abaaa. The stack is shown on the right after each step

- 1 push \$;
- 2 push S; S

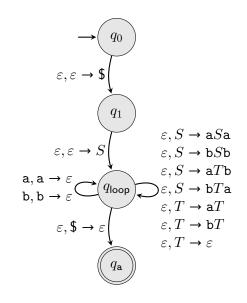
\$

aSa

Sa

bTaa\$

- **3** pop S, push aSa;
- 4 read and pop a;
- **5** pop S, push bTa;



Consider running the PDA on the input abaaa. The stack is shown on the right after each step

- 1 push \$;
- 2 push S; S

\$

aSa

Sa

bTaa\$

Taa\$

- f 3 pop S, push aSa;
- 4 read and pop a;
- **5** pop S, push bTa;
- **6** read and pop b;

 q_0 ε, ε q_1 $\varepsilon, S \rightarrow aSa$ $\varepsilon, S \rightarrow \mathbf{b}S\mathbf{b}$ $\varepsilon, \varepsilon \rightarrow$ $\varepsilon, S \rightarrow aTb$ $a, a \rightarrow \varepsilon$ $\varepsilon, S \rightarrow bTa$ q_{loop} $\varepsilon, T \rightarrow \mathbf{a}T$ $\varepsilon,T \to \mathrm{b} T$ $\varepsilon, \$ \rightarrow$ $\varepsilon, T \rightarrow \varepsilon$ q_{a}



Consider running the PDA on the input abaaa. The stack is shown on the right after each step

- 1 push \$;
- 2 push S; S

\$

aSa

Sa

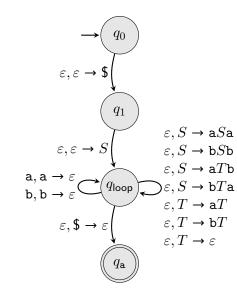
bTaa\$

Taa\$

aTaa\$

- ${f 3}$ pop S, push aSa;
- 4 read and pop a;
- **5** pop S, push bTa;
- 6 read and pop b;

7 pop T, push aT;





Consider running the PDA on the input abaaa. The stack is shown on the right after each step

- **1** push \$;
- S**2** push S;

\$

aSa

Sa

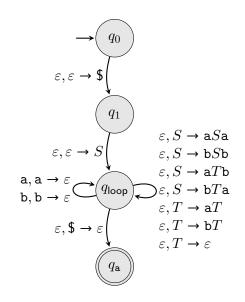
bTaa\$

Taa\$

aTaa\$

Taa\$

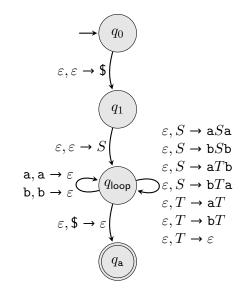
- **3** pop S, push aSa;
- 4 read and pop a;
- **5** pop S, push bTa;
- 6 read and pop b;
- \bigcirc pop T, push aT;
- 8 read and pop a;





Consider running the PDA on the input abaaa. The stack is shown on the right after each step

1 push \$; \$ S**2** push S; **3** pop S, push aSa; aSaSa4 read and pop a; **5** pop S, push bTa; bTaa\$ 6 read and pop b; Taa\$ \bigcirc pop T, push aT; aTaa\$ 8 read and pop a; Taa\$ **9** pop T, push ε ; aa\$

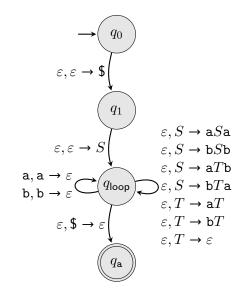




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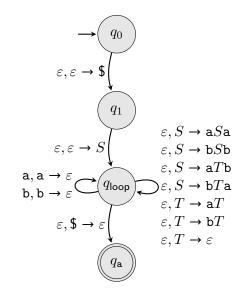


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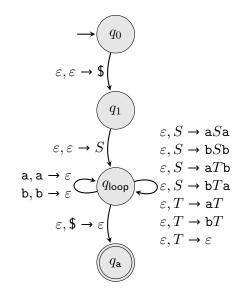
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1 push \$; **2** push S; S**3** pop S, push aSa; aSa4 read and pop a; Sa**5** pop S, push bTa; bTaa\$ 6 read and pop b; Taa\$ \bigcirc pop T, push aT; aTaa\$ 8 read and pop a; Taa\$ **9** pop T, push ε ; aa\$ a\$ (1) read and pop a; I read and pop a;



Consider running the PDA on the input abaaa. The stack is shown on the right after each step

 push \$; 	\$
2 push S ;	S
${f 3}$ pop S , push a S a;	aSa
4 read and pop a;	Sa\$
f 5 pop S , push b T a;	b T aa $\$$
6 read and pop b;	Taa\$
7) pop T , push a T ;	a T aa $\$$
8 read and pop a;	Taa
9 pop T , push $arepsilon$;	aa\$
🕕 read and pop a;	a\$
I read and pop a;	\$
pop \$ and accept;	ε



Proof.

Let A be a CFL generated by a CFG $G = (V, \Sigma, R, S)$.



Proof.

Let A be a CFL generated by a CFG $G = (V, \Sigma, R, S)$.

Construct the PDA $M = (Q, \Sigma, \Gamma, \delta, q_0, \{q_a\})$ with states $Q = \{q_0, q_1, q_{\text{loop}}, q_a\} \cup E$ where E are the extra states we need for each rule and $\Gamma = V \cup \Sigma \cup \{\$\}$.



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Start with then transitions

 $\begin{array}{l} \varepsilon, \varepsilon \to \$ \text{ from } q_0 \text{ to } q_1, \\ \varepsilon, \varepsilon \to S \text{ from } q_1 \text{ to } q_{\text{loop}}, \text{ and} \\ \varepsilon, \$ \to \varepsilon \text{ from } q_{\text{loop}} \text{ to } q_a \end{array}$



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For each $t \in \Sigma$, add the transition $t, t \to \varepsilon$ from q_{loop} to q_{loop} .



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For each $t \in \Sigma$, add the transition $t, t \to \varepsilon$ from q_{loop} to q_{loop} .

For each rule $A \rightarrow u$ add the states and transitions necessary to pop A and push u in reverse order from q_{loop} to q_{loop} .

Proof continued

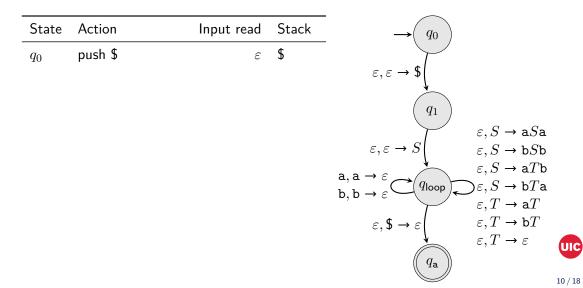
Consider running M on input $w = w_1 w_2 \cdots w_n$ for $w_i \in \Sigma$.

The first time M enters state q_{loop} , the stack is S and no input has been read.

Every subsequent time it enters q_{loop} , the input read so far concatenated with the stack is a step in some left-most derivation of w (followed by a \$).

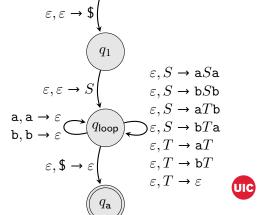
I.e., if k symbols have been read from the input and the stack is s, then $w_1w_2\cdots w_ks$ is a step in the derivation of w





 $S \Rightarrow aSa \Rightarrow abTaa \Rightarrow abaTaa \Rightarrow abaaa$

e Action	Input read	Stack		→(
push \$	ε	\$		
push S	arepsilon	S	$\varepsilon,$	$\varepsilon \rightarrow $$
push S	ε	55	$\varepsilon,$	$\varepsilon \rightarrow z$



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 $S \Rightarrow \mathbf{a}S\mathbf{a} \Rightarrow \mathbf{a}bT\mathbf{a}\mathbf{a} \Rightarrow \mathbf{a}\mathbf{b}a\mathbf{a}\mathbf{a}$

State	Action	Input read	Stack	$\rightarrow q_0$
q_0	push \$	ε	\$	
q_1	push S	ε	S	$\varepsilon, \varepsilon \rightarrow \$$
q_{loop}	pop S , push a S a	ε	aSa\$	1 1
				$\begin{pmatrix} q_1 \end{pmatrix}$
				$\varepsilon, S \to aS$
				$\varepsilon, \varepsilon \to S$ $\varepsilon, S \to bS$
				$\sim c S \rightarrow 2T$
				$\begin{array}{c} \mathbf{a}, \mathbf{a} \to \varepsilon \\ \mathbf{b}, \mathbf{b} \to \varepsilon \end{array} \qquad \qquad$
				$\varepsilon, \sigma \to aT$
				$\varepsilon, \$ \to \varepsilon \qquad \varepsilon, T \to bT$
				$\varepsilon, T \to \varepsilon$

1a

 $S \Rightarrow \mathbf{a}S\mathbf{a} \Rightarrow \mathbf{a}bT\mathbf{a}\mathbf{a} \Rightarrow \mathbf{a}\mathbf{b}a\mathbf{a}\mathbf{a}$

State	Action	Input read	Stack	$\rightarrow q_0$
q_0	push \$	ε	\$	
q_1	push S	ε	S	$\varepsilon, \varepsilon \rightarrow \$$
q_{loop}	pop S , push a S a	ε	aSa\$	
q_{loop}	read and pop a	a	Sa	$\left(\begin{array}{c} q_1 \end{array} \right)$
				$\varepsilon, \varepsilon \to S$
				$a a \rightarrow \varepsilon$
				$\begin{array}{c} \mathbf{a}, \mathbf{a} \to \varepsilon \\ \mathbf{b}, \mathbf{b} \to \varepsilon \end{array} \qquad \qquad$
				2,2 3
				$\varepsilon, \$ \rightarrow \varepsilon$
				$((q_a))$

10/18

Action	Input read	Stack	$\rightarrow q_0$	
push \$	ε	\$	\sim	
push S	ε	S	$\varepsilon, \varepsilon \to \$$	
pop S , push a S a	ε	a S a		
read and pop a	a	Sa\$	$\begin{pmatrix} q_1 \end{pmatrix}$	
pop S , push b T a	a	b T aa $\$$	$\varepsilon, S \rightarrow aSt$	a
			$\varepsilon, \varepsilon \to S$ $\varepsilon, S \to bSI$	c
			$\sum_{i=1}^{N} \varepsilon_i S \rightarrow \gamma T$	
			$a, a \to \varepsilon$ $b, b \to \varepsilon$ $(q_{\text{loop}}) \supset \varepsilon, S \to bTs$	a
			$\varepsilon, \sigma \to aT$	
			$\varepsilon, \$ \to \varepsilon$ $\varepsilon, T \to bT$	
			$\varepsilon, T \to \varepsilon$	UIC
			$\left(\begin{array}{c} q_{a} \end{array} \right)$	-
	push $\$ push S push S pop S , push aSa read and pop a	push \$ ε push S ε pop S, push aSa ε read and pop aa	push \$ ε \$push S ε S\$pop S, push aSa ε aSa\$read and pop aaSa\$	push \$ ε \$push \$ ε \$push \$ ε \$\$pop \$S\$, push a\$Sa ε read and pop aapop \$S\$, push b\$Taab\$Taa\$ $\varepsilon, \varepsilon \to S$ $\varepsilon, S \to a$Sa$\varepsilon, \varepsilon \to S\varepsilon, S \to aSa\varepsilon, \varepsilon \to S\varepsilon, S \to bSa\varepsilon, S \to bTaa\varepsilon, S \to bTaa\varepsilon, S \to \varepsilon\varepsilon, T \to b$\varepsilon, S \to \varepsilon\varepsilon, T \to b$\varepsilon, T \to \varepsilon\varepsilon, T \to \varepsilon$

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State	Action	Input read	Stack	$\rightarrow q_0$	
q_0	push \$	ε	\$		
q_1	push S	ε	S	$\varepsilon, \varepsilon \rightarrow \$$	
q_{loop}	pop S , push a S a	ε	a S a	↓ ↓	
q_{loop}	read and pop a	a	Sa	$\left(\begin{array}{c} q_1 \end{array}\right)$	
q_{loop}	pop S , push b T a	а	b T aa $\$$	$\varepsilon, S \rightarrow aSa$	
q_{loop}	read and pop b	ab	Taa\$	$\varepsilon, \varepsilon \to S$ $\varepsilon, S \to \mathbf{b}S\mathbf{b}$	
				$\epsilon, S \to aTb$	
				$\begin{array}{c} \mathbf{a}, \mathbf{a} \to \varepsilon \\ \mathbf{b}, \mathbf{b} \to \varepsilon \end{array} \qquad \qquad$	
				$\varepsilon, \sigma \to aT$	
				$\varepsilon, \$ \to \varepsilon \qquad \varepsilon, T \to bT$	
				$\varepsilon, T \to \varepsilon$	UIC
				$\left(\begin{array}{c} q_{a} \end{array} \right)$	

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State	Action	Input read	Stack	$\rightarrow q_0$
q_0	push \$	ε	\$	
q_1	push S	ε	S	$\varepsilon, \varepsilon \rightarrow \$$
q_{loop}	pop S , push a S a	ε	a S a	
q_{loop}	read and pop a	a	Sa	$\begin{pmatrix} q_1 \end{pmatrix}$
q_{loop}	pop S , push b T a	a	b T aa $\$$	$\varepsilon, S ightarrow aSa$
q_{loop}	read and pop b	ab	Taa	$\varepsilon, \varepsilon \to S \Big(\begin{array}{c} \varepsilon, \varepsilon & -2\varepsilon \\ \varepsilon, S \to \mathbf{b}S \mathbf{b} \end{array} \Big)$
q_{loop}	pop T , push a T	ab	aTaa\$	$\varepsilon S \rightarrow aTh$
				$a, a \rightarrow \varepsilon \rightarrow (a \rightarrow a) = a$
				$\mathbf{b}, \mathbf{b} \to \varepsilon \xrightarrow{q \text{loop}} \varepsilon, S \to \mathbf{b} T \mathbf{a}$ $\varepsilon, T \to \mathbf{a} T$
				$\varepsilon, \$ \to \varepsilon \Big(\qquad \varepsilon, T \to bT \Big)$
				(q_a) $\varepsilon, I \rightarrow \varepsilon$ $\bigcup c$

 $S \Rightarrow aSa \Rightarrow abTaa \Rightarrow abaTaa \Rightarrow abaaa$

State	Action	Input read	Stack	$\rightarrow q_0$	
q_0	push \$	ε	\$		
q_1	push S	ε	S	$\varepsilon, \varepsilon \to \$$	
q_{loop}	pop S , push a S a	ε	a S a $\$$		
q_{loop}	read and pop a	а	Sa	$\left(\begin{array}{c} q_1 \end{array}\right)$	
q_{loop}	pop S , push b T a	а	b T aa $\$$	$\varepsilon, S \rightarrow aSa$	
q_{loop}	read and pop b	ab	Taa	$\varepsilon, \varepsilon \to S$ $\varepsilon, S \to bSb$	
q_{loop}	pop T , push a T	ab	a T aa $\$$	$\sum_{i=1}^{n} \varepsilon_i S \to aTh$	
q_{loop}	read and pop a	aba	Taa\$	$a, a \rightarrow \varepsilon$ $(q_{loop}) \rightarrow \varepsilon S \rightarrow bTa$	
				$\mathbf{b}, \mathbf{b} \to \varepsilon \qquad \qquad$	
				$\varepsilon, \$ \to \varepsilon \Big(\qquad \varepsilon, T \to bT \Big)$	
				$\varepsilon, \bullet \to \varepsilon$	
				(q _a)	UIC

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 $S \Rightarrow aSa \Rightarrow abTaa \Rightarrow abaTaa \Rightarrow abaaa$

State	Action	Input read	Stack	$\rightarrow q_0$	
q_0	push \$	ε	\$		
q_1	push S	ε	S	$\varepsilon, \varepsilon \to \$$	
q_{loop}	pop S , push a S a	ε	a S a $\$$		
q_{loop}	read and pop a	a	Sa\$	$\begin{pmatrix} q_1 \end{pmatrix}$	
q_{loop}	pop S , push b T a	a	b T aa $\$$	$\varepsilon, S \rightarrow aSa$	
q_{loop}	read and pop b	ab	Taa $$$	$\varepsilon, \varepsilon \to S$ $\varepsilon, S \to bSb$	
q_{loop}	pop T , push a T	ab	aTaa\$	$\epsilon S \rightarrow aTh$	
q_{loop}	read and pop a	aba	Taa $$$	$a, a \to \varepsilon$	
q_{loop}	pop T , push $arepsilon$	aba	aa\$	$\mathbf{b}, \mathbf{b} \to \varepsilon \qquad \qquad$	
				$\varepsilon, \$ \to \varepsilon \qquad \varepsilon, T \to bT$	
				$\varepsilon, T \to \varepsilon$	UIC

 q_{a}

 $S \Rightarrow aSa \Rightarrow abTaa \Rightarrow abaTaa \Rightarrow abaaa$

State	Action	Input read	Stack	$\rightarrow q_0$
q_0	push \$	ε	\$	\sim
q_1	push S	ε	S	$\varepsilon, \varepsilon \rightarrow \$$
lloop	pop S , push a S a	ε	a S a $\$$	
loop	read and pop a	a	Sa	$\begin{pmatrix} q_1 \end{pmatrix}$
lloop	pop S , push b T a	a	b T aa $\$$	$\varepsilon, S \rightarrow a$
loop	read and pop b	ab	Taa	$\varepsilon, \varepsilon \to S$ $\varepsilon, S \to b$
lloop	pop T , push a T	ab	a T aa $\$$	$\sum_{i=1}^{n} \varepsilon(S \to a)$
loop	read and pop a	aba	Taa	$\begin{array}{c} \mathbf{a}, \mathbf{a} \to \varepsilon \\ \mathbf{b}, \mathbf{b} \to \varepsilon \end{array} \qquad \qquad$
loop	pop T , push $arepsilon$	aba	aa\$	$b, b \to \varepsilon$ $\varepsilon, T \to a$
loop	read and pop a	abaa	<mark>a</mark> \$	$\varepsilon, \$ \to \varepsilon \qquad \varepsilon, T \to b$
				$\varepsilon, \tau \varepsilon, T \to \varepsilon$

 $q_{\mathtt{a}}$

 $S \Rightarrow aSa \Rightarrow abTaa \Rightarrow abaTaa \Rightarrow abaaa$

				\frown
State	Action	Input read	Stack	$\rightarrow (q_0)$
q_0	push \$	ε	\$	
q_1	push S	ε	S	$\varepsilon, \varepsilon \rightarrow \$$
q_{loop}	pop S , push a S a	ε	a S a $\$$, t
q_{loop}	read and pop a	a	Sa	$\begin{pmatrix} q_1 \end{pmatrix}$
q_{loop}	pop S , push b T a	a	b T aa $\$$	$\varepsilon, S \rightarrow \epsilon$
q_{loop}	read and pop b	ab	Taa $$$	$\varepsilon, \varepsilon \to S \Big(\varepsilon, S \to \mathfrak{k} \Big)$
q_{loop}	pop T , push a T	ab	a T aa $\$$	$\epsilon S \rightarrow \epsilon$
loop	read and pop a	aba	Taa $$$	$\begin{array}{c} \mathbf{a}, \mathbf{a} \to \varepsilon \\ \mathbf{b}, \mathbf{b} \to \varepsilon \end{array} \qquad \qquad$
q_{loop}	pop T , push $arepsilon$	aba	aa\$	$b, b \rightarrow \varepsilon$ $\varepsilon, T \rightarrow \varepsilon$
q_{loop}	read and pop a	abaa	a\$	$\varepsilon, \$ \to \varepsilon \qquad \varepsilon, T \to t$
q_{loop}	read and pop a	abaaa	\$	$\varepsilon, \psi \to \varepsilon \psi$ $\varepsilon, T \to \varepsilon$
•				\bigcirc $^{\circ,1}$

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 q_{a}

UIC

 $S \Rightarrow aSa \Rightarrow abTaa \Rightarrow abaTaa \Rightarrow abaaa$

State	Action	Input read	Stack	$\rightarrow (q_0)$
q_0	push \$	ε	\$	
q_1	push S	ε	S	$\varepsilon, \varepsilon \rightarrow \$$
q_{loop}	pop S , push a S a	ε	a S a $\$$	L Contraction of the second se
q_{loop}	read and pop a	a	Sa\$	$\begin{pmatrix} q_1 \end{pmatrix}$
q_{loop}	pop S , push b T a	a	b T aa $\$$	$\varepsilon, S \rightarrow aSa$
q_{loop}	read and pop b	ab	Taa	$\varepsilon, \varepsilon \to S$ $\varepsilon, S \to bSb$
q_{loop}	pop T , push a T	ab	a T aa $\$$	$\epsilon S \rightarrow aTh$
q_{loop}	read and pop a	aba	Taa	$\begin{array}{c} \mathbf{a}, \mathbf{a} \to \varepsilon \\ \mathbf{b}, \mathbf{b} \to \varepsilon \end{array} \qquad \qquad$
q_{loop}	pop T , push $arepsilon$	aba	aa\$	$\mathbf{b}, \mathbf{b} \to \varepsilon \underbrace{\varepsilon, T}_{\varepsilon, T} \to \mathbf{a}T$
q_{loop}	read and pop a	abaa	a\$	$\varepsilon, \$ \to \varepsilon \Big(\qquad \varepsilon, T \to bT \Big)$
q_{loop}	read and pop a	abaaa	\$	$\varepsilon, \Psi \to \varepsilon \qquad \varepsilon, T \to \varepsilon$
q_{loop}	pop\$	abaaa	ε	(q_a)

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q_0	push \$	ε	\$	
q_1	push S	ε	S	$\varepsilon, \varepsilon \rightarrow \$$
q_{loop}	pop S , push a S a	ε	a S a $\$$	
q_{loop}	read and pop a	a	Sa	$\begin{pmatrix} q_1 \end{pmatrix}$
q_{loop}	pop S , push b T a	a	b T aa $\$$	$\varepsilon, S \to \mathbf{a}S$
q_{loop}	read and pop b	ab	Taa	$\varepsilon, \varepsilon \to S \left(\begin{array}{c} \varepsilon, \widetilde{\varepsilon} \to \widetilde{z}, \widetilde{\varepsilon} \\ \varepsilon, S \to \mathbf{b} S \end{array} \right)$
q_{loop}	pop T , push a T	ab	a T aa $\$$	$\sum_{i=1}^{n} \varepsilon_i S \to a_i$
q_{loop}	read and pop a	aba	Taa	$a, a \to \varepsilon$
q_{loop}	pop T , push $arepsilon$	aba	aa\$	$b, b \rightarrow \varepsilon$ (noop) $\varepsilon, S \rightarrow b$ $\varepsilon, T \rightarrow a$
q_{loop}	read and pop a	abaa	a\$	$\varepsilon, \$ \to \varepsilon $ $\varepsilon, T \to b $
q_{loop}	read and pop a	abaaa	\$	$\varepsilon, \mathfrak{y} \to \varepsilon$ $\varepsilon, T \to \varepsilon$
q_{loop}	pop\$	abaaa	ε	
q_{a}	accept	abaaa	ε	(q_{a})

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UIC

Back from example

Consider running M on input $w = w_1 w_2 \cdots w_n$ for $w_i \in \Sigma$.

The first time M enters state q_{loop} , the stack is S and no input has been read.

Every subsequent time it enters q_{loop} , the input read so far concatenated with the stack is a step in some left-most derivation of w (followed by a \$).

I.e., if k symbols have been read from the input and the stack is s, then $w_1w_2\cdots w_ks$ is a step in the derivation of w



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For each $w \in A$, there is some left-most derivation of w by G. By construction, M performs the derivation on the stack while matching leading terminals.

Thus L(M) = A.



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- **2** Next, construct a CFG that
 - has variables that are pairs of states $\langle q,r\rangle$ from the PDA;
 - has start variable $\langle q_0, q_a \rangle$;
 - has rules $\langle q,q\rangle \rightarrow \varepsilon$ for each $q \in Q$;
 - has rules $\langle p,r
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 ightarrow \langle p,q
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 - has rules $\langle p,q \rangle \to a \langle r,s \rangle b$ for $p,q,r,s \in Q$ and $a,b \in \Sigma_{\varepsilon}$ if $(r,u) \in \delta(p,a,\varepsilon)$ and $(q,\varepsilon) \in \delta(s,b,u)$



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- S Prove (by induction) that each variable ⟨q, r⟩ has the property ⟨q, r⟩ ⇒ x ∈ Σ* iff starting M in state q with an empty stack and running on input x causes M to move to state r and end with an empty stack



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4 Conclude that $\langle q_0, q_a \rangle \stackrel{*}{\Rightarrow} w$ iff $w \in L(M)$



Closure properties of CFLs

The class of context-free languages is closed under

- Union
- Concatenation
- Kleene star
- Prefix
- Suffix
- Reversal
- Intersection with a regular language
- Quotient by a string
- Quotient by a regular language

We proved closure under union, concatenation, Kleene star, and PREFIX previously



Reversal

Theorem

Context-free languages are closed under reversal.

Proof. Let B be a context-free language generated by a CFG $G = (V, \Sigma, R, S)$.

Construct CFG $G' = (V, \Sigma, R', S)$ where

 $R' = \{A \to u^{\mathcal{R}} \mid A \to u \text{ is a rule in } R\}.$



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To prove that $L(G') = B^{\mathcal{R}}$, we want to show that for each variable $A \in V$ and $u \in (V \cup \Sigma)^*$, $A \stackrel{*}{\Rightarrow}_G u$ in n steps iff $A \stackrel{*}{\Rightarrow}_{G'} u^{\mathcal{R}}$ in n steps.

Let's write $\stackrel{k}{\Rightarrow}$ to mean $\stackrel{*}{\Rightarrow}$ in exactly k steps.



Base case
$$n = 0$$
. If $A \stackrel{0}{\Rightarrow}_{G} u$, then $u = u^{\mathcal{R}} = A$ so $A \stackrel{0}{\Rightarrow}_{G'} u^{\mathcal{R}}$, and vice versa.



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Inductive step. Assume that for all n > 0, $A \in V$, and $u \in (V \cup \Sigma)^*$, $A \stackrel{n-1}{\Rightarrow}_G u$ iff $A \stackrel{n-1}{\Rightarrow}_{G'} u^{\mathcal{R}}$.



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If $A \stackrel{n}{\Rightarrow}_{G} u$, then there is some $C \in V$ and $x, y, z \in (V \cup \Sigma)^*$ such that u = xyz, $A \stackrel{n-1}{\Rightarrow}_{G} xCz$, and $C \Rightarrow_{G} y$.



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By the inductive hypothesis $A \stackrel{n-1}{\Rightarrow}_{G'} z^{\mathcal{R}} C x^{\mathcal{R}}$ and by construction $C \Rightarrow_{G'} y^{\mathcal{R}}$. Thus $A \stackrel{n}{\Rightarrow}_{G'} z^{\mathcal{R}} y^{\mathcal{R}} x^{\mathcal{R}} = (xyz)^{\mathcal{R}} = u^{\mathcal{R}}$. Swapping G and G' shows the converse.



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Thus, $A \stackrel{n}{\Rightarrow}_{G} u$ iff $A \stackrel{n}{\Rightarrow}_{G'} u^{\mathcal{R}}$.

Therefore, for $w \in B$, $S \stackrel{*}{\Rightarrow}_{G} w$ iff $S \stackrel{*}{\Rightarrow}_{G'} w^{\mathcal{R}}$ so $L(G') = B^{\mathcal{R}}$.



Suffix

Theorem

Context free languages are closed under SUFFIX.

Proof.

Since $SUFFIX(A) = PREFIX(A^{\mathcal{R}})^{\mathcal{R}}$ and CFLs are closed under reversal and PREFIX, CFLs are closed under SUFFIX.



Intersection of a CFL and a regular language

Theorem

The intersection of a CFL and a regular language is context-free.

Proof.

Let A be a CFL recognized by the PDA $M_1 = (Q_1, \Sigma, \Gamma, \delta_1, q_1, F_1)$ and B be a regular language recognized by the NFA $M_2 = (Q_2, \Sigma, \delta_2, q_2, F_2)$.



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Construct the PDA M = ($Q, \Sigma, \Gamma, \delta, q_0, F)$ where

$$\begin{aligned} Q &= Q_1 \times Q_2 \\ q_0 &= (q_1, q_2) \\ F &= F_1 \times F_2 \\ \delta((q, r), a, b) &= \{((s, t), c) \mid (s, c) \in \delta_1(q, a, b) \text{ and } t \in \delta_2(r, a)\} \quad \text{for } a \in \Sigma_{\varepsilon}, \ b, c \in \Gamma_{\varepsilon} \end{aligned}$$



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As M runs on input w, its stack and the first element of its state change according to δ_1 whereas the second element of its state changes according to δ_2 .

M accepts w iff M_1 accepts w and M_2 accepts w. Therefore, $L(M) = A \cap B$.

What about intersection with another CFL?

Are context-free languages closed under intersection?



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Consider \Sigma = \{a, b, c\} and
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A = \{\mathbf{a}^{m}\mathbf{b}^{m}\mathbf{c}^{n} \mid m, n \ge 0\}B = \{\mathbf{a}^{m}\mathbf{b}^{n}\mathbf{c}^{n} \mid m, n \ge 0\}
```

Both B and C are context-free. Is

```
A \cap B = \{\mathbf{a}^n \mathbf{b}^n \mathbf{c}^n \mid n \ge 0\}?
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How can we keep track of how many as and bs we've seen to ensure we get the same number of cs using a PDA?

How about trying to generate such strings with a CFG?



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How can we keep track of how many as and bs we've seen to ensure we get the same number of cs using a PDA?

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Next time, we'll see that $B \cap C$ is *not* context-free!

